

1 **Effects of size and anisotropy of magnetic nanoparticles associated**  
2 **with dynamics of easy axis for magnetic particle imaging**

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13 The structure of magnetic nanoparticles affects the signal intensity and resolution of magnetic particle  
14 imaging, which is derived from the harmonics caused by the nonlinear response of magnetization. To  
15 understand the key effects of particle structures on the magnetization harmonics, the dependence of the  
16 harmonics on the size and anisotropy of different structures was investigated. We measured the  
17 harmonic signals with respect to different magnetic nanoparticle structures by applying an AC field  
18 with a gradient field for magnetic particle imaging, which was compared with the numerically  
19 simulated magnetization properties. In addition, the dynamics of the easy axis of magnetic  
20 nanoparticles in the liquid state were evaluated. The difference between the harmonics in the solid and  
21 liquid states indicates the effective core size and anisotropy due to particle structures such as  
22 single-core, chainlike, and multicore particles. In the case of the chainlike structure, the difference  
23 between the harmonics in the solid and liquid states was larger than other structures. In the numerical  
24 simulations, core diameters and anisotropy constants were considered as the effective values, such as  
25 the increase in anisotropy in the chainlike structure due to dipole interaction. The multicore particles  
26 showed high harmonics owing to their large effective core diameters. The superparamagnetic regime  
27 in the multicore structure despite the large effective core diameter was derived from the small effective  
28 anisotropy. The effective core size and the effective anisotropy of each particle structure and their  
29 impacts on the harmonic signals were revealed.

30

31 Keywords: magnetic nanoparticles; magnetic particle imaging; particle structure; anisotropy; core size  
32 distribution; easy axis

33

## 1 **1. Introduction**

2 Magnetic particle imaging (MPI) was developed as an imaging method for magnetic nanoparticles  
3 (MNPs) [1]. The traceability of MPI with respect to the MNPs in blood was investigated with the time  
4 evolution of the location of MNPs in an animal model [2,3]. Cancer detection through MPI was  
5 conducted by using MNPs functionalized with materials conjugating with cancer cells, such as  
6 lactoferrin, which is a peptide, to target brain cancer [4,5]. Monitoring the transplantation of  
7 magnetically functionalized stem cells using MPI was examined to promote the efficacy of stem cell  
8 therapy, such as the regeneration of cardiac tissue [6,7]. Islet transplantation was successfully  
9 conducted by labeling pancreatic islets using MNPs for MPI monitoring [8].

10 MNPs with large-amplitude harmonics were investigated to advance MPI. Harmonic amplitude is  
11 influenced by the size and structure of MNPs [9]. In general, MNPs with a large core diameter  
12 exhibited nonlinear response to an applied field of low flux density, which induced the large-amplitude  
13 harmonics [10,11]. It was also been found that the core diameter of 24.4 nm showed the clearest image  
14 in the core diameters from 18.5 nm to 32.1 nm with low anisotropy [12]. With regard to the structural  
15 effect, the multicore structure provided the large-amplitude harmonics [13]. Multicore particles are  
16 composed of a large effective core as the aggregated single-core particles [14]. The magnetization  
17 behavior of the multicore structure is influenced not by each single-core diameter, but by the effective  
18 cluster diameter [15].

19 The difference between the harmonic amplitude in the solid and liquid states indicates that the MNPs  
20 fixed in a tumor are distinguished from the MNPs dispersed in blood in the human body with respect  
21 to MPI signals [9]. Only magnetization is rotated without changing the spatial rotation of the particle  
22 volume in the solid state, which is observed as Néel relaxation. On the contrary, the easy axes rotate in  
23 addition to magnetization in the liquid state as Brownian relaxation. The viscosity of the medium  
24 associated with Brownian relaxation time significantly affects the magnetization dynamics through the  
25 change in the dynamics of the easy axis [16–18]. We clearly observed easy-axis rotation with time  
26 delay from magnetization rotation by applying pulse fields as a transition response [19]. The influence  
27 of particle core diameters associated with the anisotropy energy on the rotational degree of the easy  
28 axis was evaluated. Furthermore, the dynamics of the easy axis of the MNPs dispersed in liquid were  
29 numerically and experimentally observed as a static response [16,20].

30 In this study, MPI signals were measured for blood-pooling MNPs of different sizes and structures. We  
31 evaluated the effect of the core size and anisotropy associated with particle structure on the harmonic  
32 derived from the nonlinear response of MNPs. Moreover, the influence of the dynamics of the easy  
33 axis on the harmonic in the liquid state was assessed.

34

## 35 **2. Materials and Methods**

### 36 **2.1. Measured MNPs**

37 The following water-based maghemite nanoparticles, which were supplied by Meito Sangyo Co. Ltd.,

1 Kiyosu, Japan, were analyzed: CMEADM-004 (sample I), CMEADM-023 (sample II),  
2 CMEADM-033 (sample III), and CMEADM-033-02 (sample IV). These MNPs were coated by  
3 carboxymethyl-diethylaminoethyl dextran, which is negatively charged and enhances the  
4 blood-pooling capability of MNPs [21]. For Samples I, II, III, and IV, the mean core diameters  
5 measured with a transmission electronic microscopy (TEM) were 4, 8, 5–6, and 6 nm, the mean  
6 hydrodynamic diameters measured by dynamic light scattering were 38, 83, 54, and 64 nm, and the  
7 saturation magnetic moments measured by the DC magnetization curves were 98, 113, 104, and 119  
8  $\text{A}\cdot\text{m}^2/\text{kg}\text{-Fe}$ , respectively [9]. The concentration of the analyzed samples was 28 mg-Fe/mL.

9

## 10 **2.2. Measurement of 2D MPI and AC magnetic properties**

11 A set of permanent magnets, a set of two drive coils to apply an AC field, and a pick-up coil including  
12 a differential coil were prepared to measure the third harmonic magnetization as the signal for 2D MPI.  
13 A gradient field was applied to select the field free point (FFP) using the permanent magnets, whose  
14 gradient was 1 T/m along the x-axis and 2 T/m along the y-axis. The maximal flux density and  
15 frequency of the applied AC field were 3.5 mT and 3 kHz, respectively. The 2D images were  
16 constructed by directly plotting the real part of the measured third harmonic in the x-y plane. The  
17 position of the FFP and the set of detection coils were fixed. The sample position was moved to scan  
18 samples for 2D MPI. The real part of the third harmonic was detected by a lock-in amplifier.

19 In addition, the magnetization signals of each sample were measured in an AC field with the maximal  
20 flux density of 10 mT and frequency of 10 kHz, using a detection circuit that included pick-up and  
21 differential coils located in an excitation coil without the gradient field [9]. The signal derived from  
22 the applied field was reduced by the differential coil, and was completely canceled out by subtracting  
23 the signal detected from the pick-up coil without samples from the signal with samples. To evaluate  
24 the nonlinear response of the magnetization to the applied AC field, the third harmonic was analyzed  
25 from the measured magnetization signal with the Fourier transform method.

26

## 27 **2.3. Numerical simulation**

28 The dynamics of the magnetization with the rotation of the easy axis in the liquid state are calculated  
29 using [16,22,23]

$$30 \frac{d\mathbf{m}}{dt} = \boldsymbol{\omega} \times \mathbf{m} - \frac{\gamma}{1 + \alpha^2} \left[ \mathbf{m} \times \left( \mathbf{H}_{\text{eff}} - \frac{\boldsymbol{\omega}}{\gamma} \right) + \alpha \mathbf{m} \times \left\{ \mathbf{m} \times \left( \mathbf{H}_{\text{eff}} - \frac{\boldsymbol{\omega}}{\gamma} \right) \right\} \right], \quad (1)$$

31 where  $\mathbf{m}$ ,  $\gamma$ ,  $\alpha$ ,  $\mathbf{H}_{\text{eff}}$ , and  $\boldsymbol{\omega}$  are the magnetic moment, gyromagnetic ratio, damping parameter ( $\alpha = 0.1$ ),  
32 effective field, and angular velocity of a particle, respectively. Magnetic moment was calculated as the  
33 value normalized by saturated magnetic moment  $M_s$  in MKSA system of units. The gyromagnetic ratio  
34 is estimated as  $\gamma = \mu_0 M_s V_M (1 + \alpha^2) / (2\alpha \tau_N k_B T)$ , where  $\mu_0$  is the permeability of free space,  $V_M$  is the  
35 volume of a single-domain particle,  $\tau_N$  is the zero-field Néel relaxation time,  $k_B$  is the Boltzmann  
36 constant ( $1.38 \times 10^{-23}$  J/K), and  $T$  is the temperature in Kelvin [24]. The effective field is composed of  
37 the excitation field ( $\mathbf{H}_{\text{ex}}$ ), anisotropy field ( $\mathbf{H}_{\text{an}}$ ), and fluctuating field ( $\mathbf{H}_{\text{th}}$ ) due to thermal disturbance

1 to consider the Zeeman, anisotropy, and thermal energies associated with MNPs, respectively. The  
2 anisotropy field is estimated as  $\mathbf{H}_{\text{an}}=2K_u(\mathbf{m}\cdot\mathbf{n})\mathbf{n}/(\mu_0M_s)$ , where  $K_u$  is the effective anisotropy constant  
3 including crystal, surface, and shape effects, and  $\mathbf{n}$  is the unit vector of the easy axis. In addition, the  
4 angular velocity associated with particle rotation is given by

$$5 \quad \boldsymbol{\omega} = \frac{1}{\zeta} \{ \mu_0 M_s V_M \mathbf{m} \times (\mathbf{H}_{\text{ex}} + \mathbf{H}_{\text{th}}) + \boldsymbol{\Gamma} \}, \quad (2)$$

6 where  $\zeta$  and  $\boldsymbol{\Gamma}$  are the friction coefficient and random torque due to thermal fluctuation, respectively.  
7 The friction coefficient depends on viscosity  $\eta$  and particle hydrodynamic volume  $V_H$ . It is estimated  
8 by  $\zeta = 6\eta V_H$ , which is originally applied for spherical particles. In the chainlike structure, the shape  
9 anisotropy was increased by the dipole interaction as the shape effect. In this simulation, particularly  
10 to evaluate the influences of the effective size and the effective anisotropy of MNPs on the harmonics,  
11 the parameters other than the size and anisotropy is not changed. In addition, because a thermal  
12 fluctuation field affects the magnetization and the random torque affects the easy axis, these factors are  
13 separately defined. The fluctuating field and random torque due to thermal disturbance have Gaussian  
14 distributions with zero mean. The variance of the zero mean fluctuating field and random torque due to  
15 thermal disturbance satisfied the following equations:

$$16 \quad \langle H_{th,i}(t)H_{th,j}(t') \rangle = \frac{2\alpha}{1+\alpha^2} \frac{k_B T}{\gamma \mu_0 M_s V_M} \delta_{ij} \delta(t-t'), \quad (3)$$

$$17 \quad \langle \Gamma_i(t)\Gamma_j(t') \rangle = 2\xi k_B T \delta_{ij} \delta(t-t'), \quad (4)$$

18 In eqs. (3) and (4),  $i$  and  $j$  are Cartesian indices of different particles.  $\delta_{ij}$  is the Kronecker delta function,  
19 and  $\delta$  is the Dirac delta function. The orientation of the easy axis is calculated by the differential  
20 equation of the unit vector of the easy axis, as follows:  $d\mathbf{n}/dt = \boldsymbol{\omega} \times \mathbf{n}$ . The differential equations in  
21 terms of the numerical simulations were solved with the Runge–Kutta method.

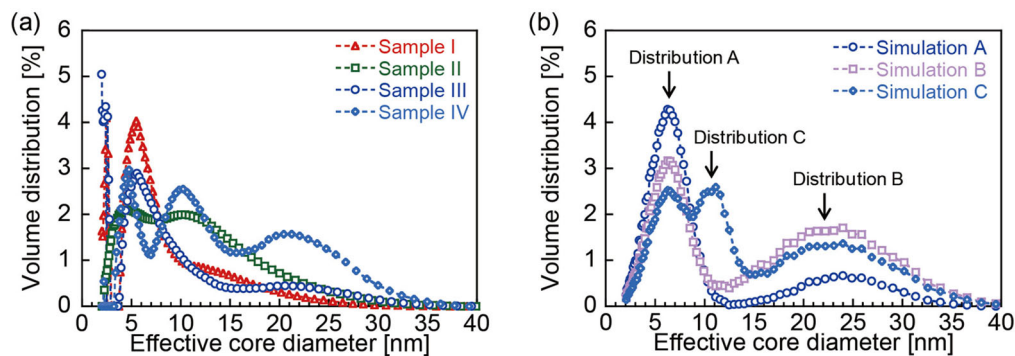
22 With respect to the model in the solid state, the term including  $\boldsymbol{\omega}$  was omitted in Eq. (1). In the  
23 numerical simulations, 28672 particles were set. A saturation magnetic moment of  $96 \text{ A}\cdot\text{m}^2/\text{kg-Fe}$  was  
24 applied to all particles. In particular, the hydrodynamic particles in the experiment are composed of the  
25 aggregated core particles, which is complex matter. To simplify the simulation model, the  
26 hydrodynamic diameter was equal to the effective core diameter. The temperature was 300 K, and the  
27 viscosity was  $0.89 \text{ mPa}\cdot\text{s}$ . The flux density and frequency of the applied field were 10 mT and 10 kHz,  
28 respectively.

29

#### 30 **2.4. Size distribution of MNP in experiments and numerical simulations**

31 Figure 1(a) shows the volume distributions normalized by the total volume with respect to the core  
32 diameter of each sample estimated from DC magnetization curves [25]. The DC magnetization curves  
33 were measured in our previous research [9]. The size distributions show the effective core diameters  
34 for each sample, including the single-core, chainlike, and multicore structures, which were observed  
35 by a TEM and magnetization measurements in Ref. [9]. The peaks for the small size distributions of  
36 5.4, 7.4, 5.2, and 4.7 nm in samples I, II, III, and IV, respectively, indicated MNPs of the single core

1 structure. The peaks for the multicore structure were confirmed at 20–21 nm in samples III and IV. In  
2 addition, the peaks at 10–11 nm in samples II and IV corresponded to the chainlike structure.  
3 Figure 1(b) shows the effective core size distribution in the numerical simulation, which is determined  
4 from the size distributions of samples III and IV shown in Fig. 1(a). Distributions A, B, and C included  
5 the effective core particles with sizes of  $5.5 \pm 3$ ,  $20.5 \pm 6.5$ , and  $10 \pm 2$  nm (mean  $\pm$  SD) between the  
6 diameters of 2–40 nm, which indicated the single-core, multicore, and chainlike structures,  
7 respectively. Simulations A and B were the sum of the distributions A and B. Simulation C was the  
8 sum of the distributions A, B, and C. The ratios of each distribution in simulations A–C were also  
9 determined from the ratios of the distribution in samples III and IV. To evaluate the dependence of the  
10 particle structures on the harmonic properties in the same distribution with respect to each structure,  
11 distributions A–C were prepared instead of the exact size distribution in Fig. 1(a).



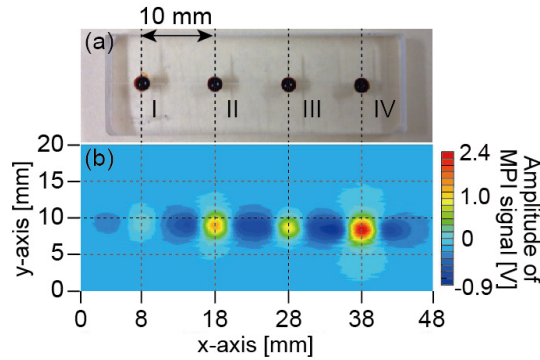
12  
13 **Fig. 1.** (a) Volume distribution of the effective core diameters in Samples I, II, III, and IV estimated  
14 from DC magnetization measurements. (b) Volume distribution of the effective core diameters for the  
15 numerical simulations determined from (a). The effective core particles of  $5.5 \pm 3$ ,  $20.5 \pm 6.5$ , and  $10 \pm$   
16  $2$  nm (mean  $\pm$  SD) between the diameters of 2–40 nm were included in distributions A, B, and C.

### 17 18 **3. Results and Discussion**

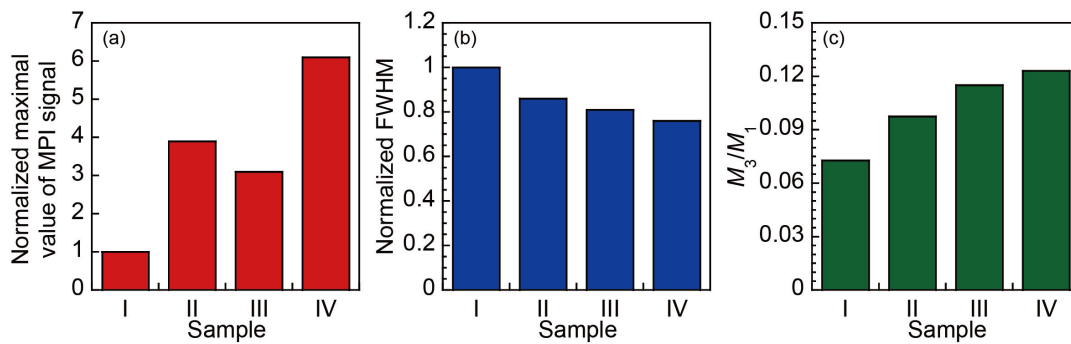
#### 19 **3.1. 2D image of MPI and harmonic properties**

20 Figure 2 shows the 2D images obtained by scanning each sample using the measurement system. The  
21 maximal value and the full width at half maximum (FWHM) of the real part of the third harmonic as  
22 the MPI signal in Fig. 2 are shown in Figs. 3(a) and (b). These values are dimensionless parameters  
23 because they are normalized by the values for sample I. The negative values of the real part of the  
24 third harmonic shown in Fig. 2 were derived from the magnetization response to the AC drive field  
25 with the DC bias field out of the FFP. When the FFP was located in the position without the samples,  
26 the large amplitude of the DC gradient field was applied to the samples. The maximal value of the  
27 MPI signal in sample II is higher than those of samples I and III because its core diameter is larger  
28 than those of the other two samples. The MPI signal of sample IV is higher than those of the other  
29 samples because the MNPs with large magnetization were collected through magnetic separation.  
30 Figure 3(c) shows the third harmonic amplitude ( $M_3$ ) normalized by fundamental amplitude  $M_1$ , i.e.,  
31  $M_3/M_1$ . The value of  $M_3/M_1$  depends on the samples, similar to the FWHM values associated with the

1 nonlinearity of magnetization response to the applied field. When  $M_3/M_1$  increased, the FWHM value  
 2 decreased with regard to the measured samples (Fig. 3(c)). The high  $M_3/M_1$  and the low FWHM  
 3 indicates the high resolution for the MPI.



4  
 5 **Fig. 2.** (a) Measured MNPs in the sample holder and (b) 2D images as the distributions of the MPI  
 6 signal amplitude in samples I, II, III, and IV. The gradient field is 1 T/m along the x-axis and 2 T/m  
 7 along the y-axis. The flux density and frequency of the applied AC field are 3.5 mT and 3 kHz,  
 8 respectively.



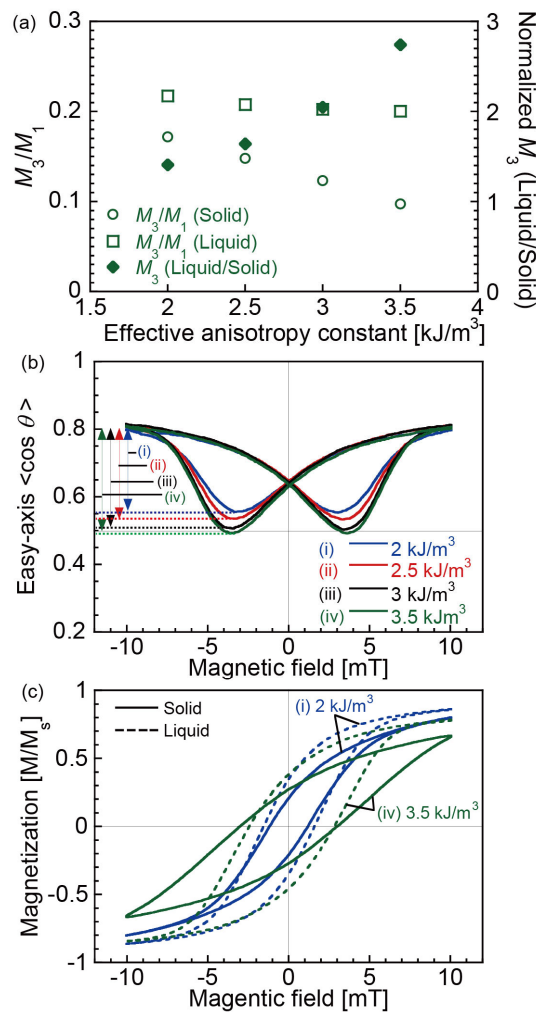
9  
 10 **Fig. 3.** (a) Maximal values and (b) the full width at half maximum (FWHM) of the real part of the  
 11 third harmonic as the MPI signals normalized by the values for Sample I with respect to the 2D images  
 12 shown in Fig. 2. (c) The third harmonic amplitude ( $M_3$ ) normalized by fundamental amplitude  $M_1$   
 13 ( $M_3/M_1$ ) measured without the gradient field. The flux density and frequency of the applied AC field  
 14 are 10 mT and 10 kHz, respectively.

### 16 3.2. Numerical simulations in multicore structures with large effective core diameter

#### 17 3.2.1. Effects of effective anisotropy on harmonic properties

18 The dependence of  $M_3/M_1$  and  $M_3$  (liquid/solid) on the anisotropy constant is evaluated with respect to  
 19 the multicore structure shown as distribution B in Fig. 4(a). As the anisotropy constant increases,  
 20  $M_3/M_1$  and the ratio of  $M_3$  in the liquid state to that in the solid state, i.e.,  $M_3$  (liquid/solid), first  
 21 decrease and then increase. Figure 4(b) shows the rotational degree of the easy axis,  $\langle \cos \theta \rangle$ , where  $\theta$   
 22 is the angle between the directions of the easy axis and applied field. The rotation of the easy axis is  
 23 delayed from the applied field because of the long Brownian relaxation times of the distributed  
 24 particles. The range between the maximal and minimal rotational degrees of the easy axis increases

1 with the anisotropy constant. In the case of low anisotropy, the easy axis is steadily oriented in the  
 2 direction of the applied field because the lowest  $\langle \cos \theta \rangle$  is higher than 0.5 in Fig. 4(b).  
 3 Figure 4(c) shows the magnetization curves with effective anisotropy constants of 2 and 3.5 kJ/m<sup>3</sup> in  
 4 Fig. 4(a). The maximal magnetizations in both the solid and liquid states decreased with the increase  
 5 in the anisotropy constant. In the solid state, the large anisotropy energy barrier inhibited the  
 6 magnetization. In the liquid state, the magnetization rotation was also inhibited by the anisotropy in  
 7 spite of the rotation of the easy-axis. It is indicated that the magnetization in the liquid state is easy to  
 8 orient in the direction of the applied field in the condition of the constant orientation of the easy axis in  
 9 the direction of the applied field compared to the condition where the easy axis rotates along with the  
 10 magnetization by large anisotropy [26–28].



11  
 12 **Fig. 4.** Dependence of (a) the third harmonic amplitude ( $M_3$ ) normalized by the fundamental amplitude  
 13  $M_1$ ,  $M_3/M_1$ , the ratio of  $M_3$  in the liquid state to that in the solid state,  $M_3$  (liquid/solid), and (b) the  
 14 rotational degree of the easy axis,  $\langle \cos \theta \rangle$ , on the effective anisotropy constant for multicore particles.  
 15  $\theta$  is the angle between the easy axis and applied field. The distribution of the particle diameters is the  
 16 same as distribution B. (c) AC magnetization curves in the anisotropy constants of 2 and 3.5 kJ/m<sup>3</sup> are  
 17 also shown. The flux density and frequency of the AC field are 10 mT and 10 kHz, respectively.

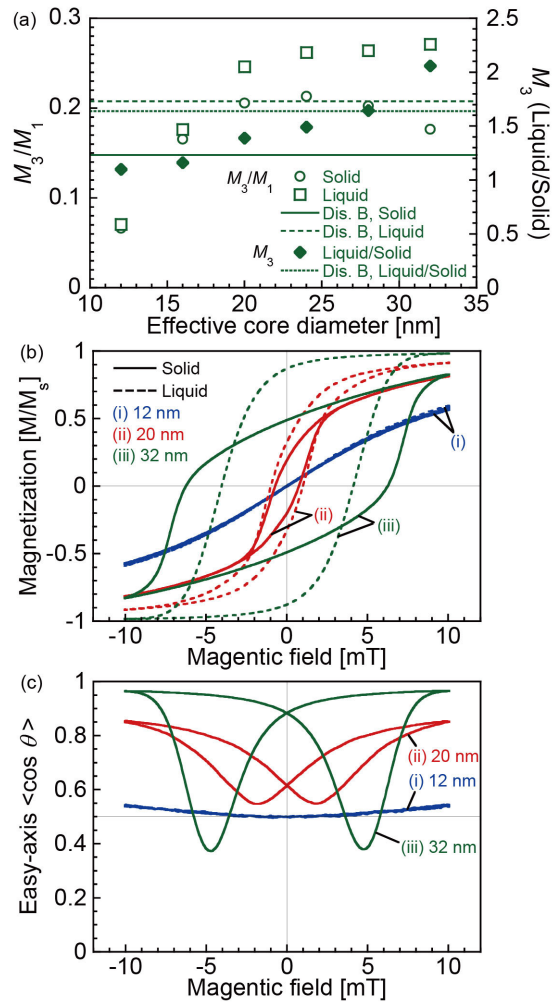
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### 1 **3.2.2. Effects of effective core size on harmonic properties**

2 Figure 5(a) shows the  $M_3/M_1$  and  $M_3$  (liquid/solid) of individual particles with different core diameters  
3 in distribution B as multicore particles in the solid and liquid states. The effective anisotropy constant  
4 was  $2.5 \text{ kJ/m}^3$  in Fig. 5. Basically,  $M_3/M_1$  and  $M_3$  (liquid/solid) increase with core diameters owing to  
5 the increase in magnetization and anisotropy energy. With respect to the MNPs with core diameters  
6 larger than 24 nm,  $M_3/M_1$  decreases with core diameters because the anisotropy energy barrier is too  
7 high for the magnetization to overcome. The magnetization curves shown in Fig. 5(b) indicate that the  
8 magnetization is gradually changed from the superparamagnetic regime of the small core diameter to  
9 the ferromagnetic regime of the large core diameter in the solid state. In the case of multicore particles,  
10 it is easier for magnetization to overcome the anisotropy energy barrier compared to the case of  
11 single-core and chainlike particles because of large effective core diameter and low effective  
12 anisotropy. In particular, the multicore particles with small core diameters indicate the magnetization  
13 response based on the Langevin equation as the superparamagnetic regime.

14 The magnetization curve for the core diameter of 12 nm in the liquid state is marginally changed from  
15 that in the solid state because of low anisotropy energy. The rotational degree of the easy axis is small  
16 in the core diameter of 12 nm and increases with the increment in diameter (Fig. 5(c)). When the  
17 anisotropy energy is low, the easy axis simply orients toward the direction of the applied field and  
18 relaxes in the low flux density of the applied field. In addition, with respect to the rotation of the easy  
19 axis, the phase delay from the applied field also increases with the increment in the core diameter,  
20 because of long Brownian relaxation times in the large hydrodynamic diameters. In particular,  $\langle \cos \theta \rangle$   
21 is smaller than 0.5 in the core diameter of 32 nm around the lowest peak values. It is indicated that the  
22 easy axis distributes toward the direction perpendicular to the applied field.





1  
 2 **Fig. 5.** Dependence of (a) the third harmonic amplitude ( $M_3$ ) normalized by the fundamental amplitude  
 3  $M_1$ ,  $M_3/M_1$ , the ratio of  $M_3$  in the liquid state to that in the solid state,  $M_3$  (liquid/solid), on the effective  
 4 core diameters including distribution B as multicore particles. (b) The rotational degree of the easy  
 5 axis,  $\langle \cos \theta \rangle$ , and (c) AC magnetization curves for the core diameters of 12, 20, and 32 nm were  
 6 observed.  $\theta$  is the angle between the easy axis and applied field. The flux density and frequency of the  
 7 AC field are 10 mT and 10 kHz, respectively.

8

### 9 **3.2.3. Models of magnetization and easy axis responding to magnetic field**

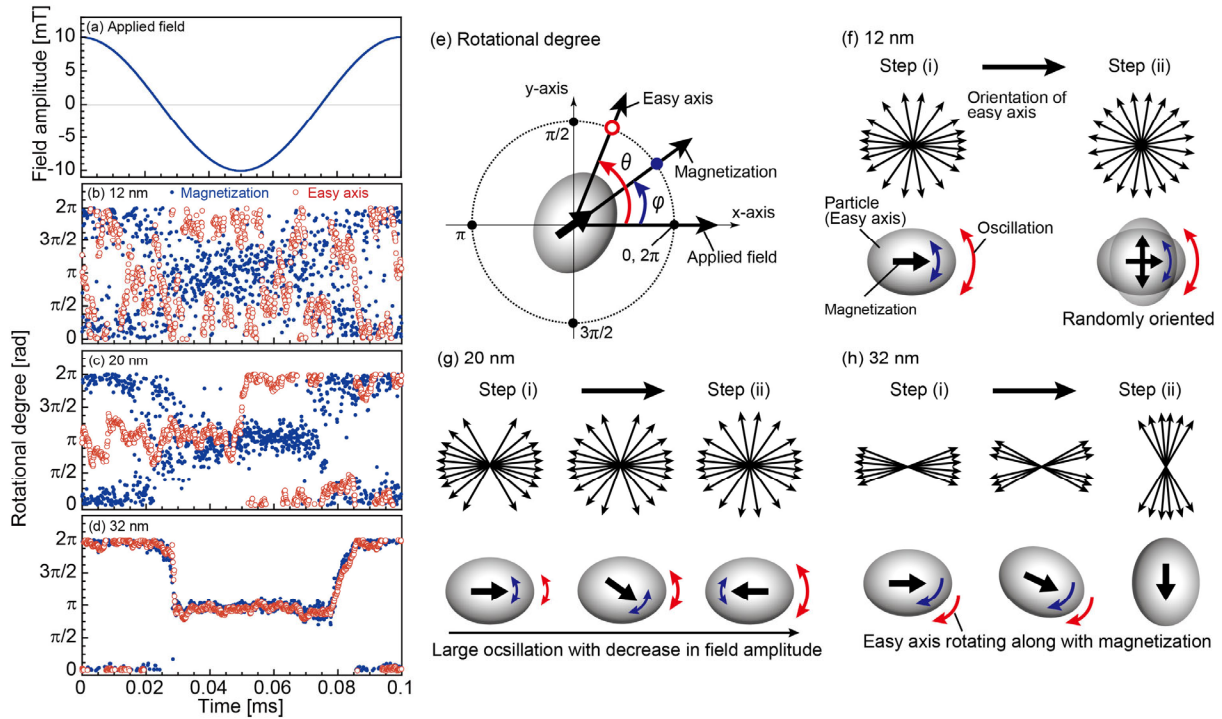
10 To prove the traceability of the easy axis to the magnetization in large core diameters, the time  
 11 evolutions of the direction of the easy axes with respect to the different core diameters are observed in  
 12 terms of a randomly extracted single particle (Figs. 6(a–d)). Figure 6(e) corresponds to the relation  
 13 between the single particle model and the rotational degrees. The rotational degree of 0 and  $2\pi$  showed  
 14 the same condition. The positive direction of the applied field was shown as the degree of 0 or  $2\pi$ , and  
 15 its negative direction was shown as the degree of  $\pi$ . In addition, with respect to the easy axis, the  
 16 origin symmetry is applied because the potential energy  $E = K_u V_M \sin^2(\theta - \varphi) - \mu_0 M_s V_M \cos(\theta)$ , which is  
 17 indicated by the Stoner-Wohlfarth model, is same in the origin symmetry [29]. The angle between the

1 magnetization and the applied field was  $\varphi$ . In Figs. 6(b–d),  $\theta$  and  $\varphi$  were observed as the rotational  
2 degree of the easy axis and the magnetization, respectively.

3 Figures 6(f–h) illustrates the distributions of the easy axis and the models of the single particle for  
4 each diameter. First, it is indicated that the influence of the thermal disturbance on the magnetization  
5 decreases with the increase in core diameter because of the large potential energy. The direction of the  
6 easy axis is marginally related to that of the magnetization because of the low anisotropy energy in a  
7 small core diameter such as 12 nm (Fig. 6(f)). The easy axis is fully relaxed in the zero field and  
8 shows the lowest distribution (Figs. 5(c) and 6(f)). When the anisotropy energy is high owing to a  
9 large core diameter such as 32 nm, the easy axis significantly traces the direction of the magnetization  
10 rotation (Fig. 6(d)). When the direction of the magnetization is reversed, the easy axis tends to  
11 distribute toward the direction perpendicular to the applied field with the rotational degree around  $\pi/2$   
12 or  $3\pi/2$  as shown in Figs. 6(d, h), which corresponds to the  $\langle \cos \theta \rangle$  lower than 0.5 in Fig. 5(c). In the  
13 core diameter of 20 nm, the easy axis tends to orient and oscillate around the direction of the applied  
14 field (Fig. 6(c)). The easy axis quasi relaxes in the low flux density of the applied field with constant  
15 orientation toward the direction of the applied field (Fig. 6(g)). The magnetization has already  
16 reversed in the lowest rotational degree of the easy axis in the core diameter of 20 nm because the  
17 anisotropy energy is not large enough to bind the magnetization to the easy axis in the low flux density  
18 of the applied field (Figs. 5(b), 5(c), and 6(g)). In addition, it is indicated that the reversal of the easy  
19 axis from the rotational degree around  $\pi$  to that around  $2\pi$  in the duration around 0.05 ms in Fig. 6(c)  
20 is due to thermal disturbance, and marginally affects the rotation of the magnetization because of the  
21 origin symmetry of the easy axis. When the applied field showed a positive value, the dots of the  
22 magnetization and the easy axis were distributed from 0 to  $\pi/2$  and from  $3\pi/2$  to  $2\pi$ . This indicates the  
23 oscillation of the magnetization and the easy axis around the rotational degree of 0 as the direction of  
24 the applied field due to the thermal disturbance.

25 In terms of the high anisotropy energy, the case of large core diameters is similar to the case of a large  
26 anisotropy constant. In Fig. 5(c), the maximal rotational degree of the easy axis increases with the  
27 increase in core diameter owing to the large magnetic torque [30]. However, it is constant regardless of  
28 the anisotropy constant (Fig. 4(b)). Thus, the traceability of the easy axis to the magnetization is  
29 determined by the anisotropy energy associated with both core diameter and anisotropy constant. The  
30 maximal rotational degree of the easy axis is influenced by the core diameter affecting the magnetic  
31 torque. The ratios of the Néel relaxation time  $\tau_N$  to the Brownian relaxation time  $\tau_B$  ( $\tau_N/\tau_B$ ) were 0.0030,  
32 0.0026, and 0.79 for the core diameters of 12, 20, and 32 nm, respectively. At the intercept point for  
33 the Néel and Brownian relaxation times, the core diameter was 32.3 nm in  $2.5 \text{ kJ/m}^3$  of the anisotropy  
34 constant. Even though the relation of  $\tau_B \gg \tau_N$  was confirmed in 12 and 20 nm, the traceability of the  
35 easy axis to the magnetization was enhanced in 20 nm. It was found that the traceability of the easy  
36 axis is dependent on the anisotropy energy rather than the ratio of the relaxation time  $\tau_N/\tau_B$ , despite the  
37 large value of  $\tau_N/\tau_B$  in 32 nm.

1



2

3 **Fig. 6.** Time evolution of (a) the flux density of applied field, and the magnetization and easy axis of a  
 4 randomly extracted single particle for the core diameters of (b) 12 nm, (c) 20 nm, and (d) 32 nm. The  
 5 solid and open dots show the magnetization and easy axis, respectively. The frequency of the applied  
 6 field was 10 kHz. (e) relation between the single particle model and the rotational degrees. The  
 7 rotational degrees of 0 and  $2\pi$  denote the same condition. The directions of the applied field were the  
 8 rotational degrees of 0 (positive direction) and  $\pi$  (negative direction). Distributions of the easy axis  
 9 and the single-particle models for the core diameters of (f) 12 nm, (g) 20 nm, and (h) 32 nm in the  
 10 maximal flux density of the applied field (Step (i)) and the lowest distribution of the easy axis in Fig.  
 11 5(c) (Step (ii)). The arrows distributed in a circular pattern show the orientation of the easy axis as the  
 12 model of the total distribution of the easy axis in Fig. 5(c).

13

14 **3.3. Effective magnetism in characteristic structures of MNPs determined from experiments and**  
 15 **numerical simulations**

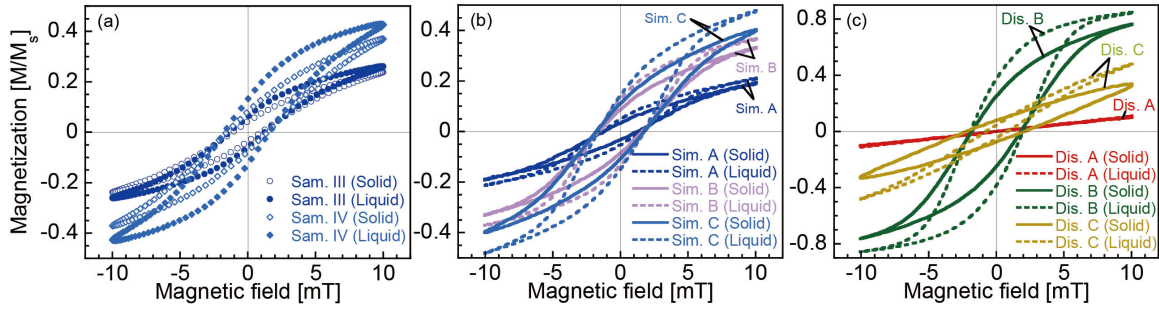
16 Figures 7(a) and (b) show the AC magnetization curves obtained for samples III and IV and for  
 17 simulations A, B, and C, respectively, in the solid and liquid states. Samples III and IV were choose as  
 18 the experimental results for the comparison with the results of the numerical simulation because  
 19 sample IV was the sample magnetically separated from sample III. The effects of the core diameter  
 20 and anisotropy on the nonlinear response of the magnetization is clearly observed in samples III and  
 21 IV. The harmonic properties dependent on the particle structures were confirmed in the range of 1–100  
 22 kHz, and their frequency dependence has been discussed in our previous research [9]. The amplitude  
 23 of the third harmonic decreased with the increase in frequency with the phase delay from the applied  
 24 field.

1 The AC magnetization curves in distributions A, B, and C are shown in Fig. 7(c). In distributions A  
2 and C as the single-core and chainlike structures, the effective anisotropy constant was  $16 \text{ kJ/m}^3$ . With  
3 respect to the single-core particle of the small core diameter, the surface anisotropy was large [31]. In  
4 the chainlike structure, the dipole interaction enhances the uniaxial anisotropy as the shape effect  
5 [32,33]. The effective anisotropy constant was determined as  $2.5 \text{ kJ/m}^3$  in distribution B.  $M_3$  and  
6  $M_3/M_1$  were evaluated using the AC magnetization signals, and they are shown in Table 1. The  $M_3$  and  
7  $M_3/M_1$  of simulation B are larger than those of simulation A because of the high distribution of the  
8 multicore structures in simulation B. However,  $M_3$  (liquid/solid) in simulations A and B is similar to  
9 that of distribution B. The influence of the  $M_3$  derived from multicore particles on the total  $M_3$  of the  
10 sample is dominant in comparison with the single-core particles. Even though the  $M_3$  of simulation C  
11 is larger than that of simulation B, the  $M_3/M_1$  of simulation C is smaller than that of simulation B. The  
12  $M_3$  (liquid/solid) of distribution C is significantly larger than that of distribution B. Both  $M_3/M_1$  and  $M_3$   
13 (liquid/solid) in sample IV were larger than those in sample III. The ratio of the multicore and  
14 chainlike structures in sample IV was found to increase compared to sample III, which is characterized  
15 by the peaks in 10–11 nm and 20–21 nm ranges of the size distribution in Fig. 1(a). In particular, the  
16 steep slope of the magnetization curve associated with the nonlinear response of the magnetization  
17 was shown by  $M_3/M_1$ .

18 In the superparamagnetic regime, the coercivity in the liquid state was larger than that in the solid state  
19 because the Brownian relaxation occurred with the Néel relaxation in the liquid state, and the phase  
20 delay of the magnetization increased in the liquid state. On the other hand, the coercivity decreased in  
21 the ferromagnetic particles except for the effect of the magnetic relaxation because the easy axis  
22 rotated along with the magnetization and the anisotropy energy barrier declined in the liquid state. The  
23 anisotropy of the chainlike structure binds the magnetization to the easy axis and induces the  
24 ferromagnetic regime in the solid state. In distribution C, the coercivity in the liquid state was smaller  
25 than that in the solid state. Distribution C showed the strong ferromagnetic regime, which resulted in  
26 the high  $M_3$ (liquid/solid) value. The magnetization in the solid state was inhibited by the high  
27 anisotropy energy barrier in comparison with that in the liquid state. The effective transition from the  
28 ferromagnetic regime in the solid state to the superparamagnetic regime in the liquid state was also  
29 observed as the lower imaginary part of susceptibility in the liquid state than that in the solid state [34].  
30 In terms of the chainlike structure, when the easy axis is rotatable in the liquid state, high anisotropy  
31 promotes the rotation of the easy axis, which results in the nonlinear response of the magnetization  
32 [17,31].

33 As shown in Fig. 4(c), as the coercivity in the liquid state is smaller than that in the solid state with an  
34 effective anisotropy constant of  $3.5 \text{ kJ/m}^3$ , which is lower than the bulk magnetocrystalline anisotropy  
35 constant of  $\gamma\text{-Fe}_2\text{O}_3$  ( $4.6 \text{ kJ/m}^3$ ) [34]. On the other hand, the AC magnetization curves in samples III  
36 and IV including the multicore structure, the coercivity in the liquid state was slightly larger than that  
37 in the solid state due to the Brownian relaxation. With respect to the multicore structure, the

1 superparamagnetic regime was dominant, and the effective anisotropy constant lower than  $2.5 \text{ kJ/m}^3$  in  
2 the numerical simulation in Fig. 7 was applicable. In contrast to the demagnetizing effect of the dipole  
3 interaction in the short interparticle distance [35,36], the effective magnetization in the multicore  
4 structure is enhanced compared to the single-core particle. In the multicore structure, the role of the  
5 exchange interaction is dominant, which is associated with the superparamagnetic regime [37]. It is  
6 indicated that the isotropic behavior in the multicore structure was due to the magnetic coupling  
7 among the randomly aggregated core particles.



8  
9 **Fig. 7.** AC magnetization curves of (a) samples (sam.) III and IV, (b) simulations (sim.) A, B, and C,  
10 and (c) distributions (dis.) A, B, and C in the solid and liquid states. The flux density and frequency of  
11 the applied AC field are 10 mT and 10 kHz, respectively, in all cases. The measured results are shown  
12 in (a). The results in (b) and (c) are numerically simulated.

13  
14 **Table 1.** Third harmonic  $M_3$  in solid and liquid states, the ratio of  $M_3$  in the liquid state to that in the  
15 solid state,  $M_3$  (liquid/solid), and  $M_3$  normalized by fundamental amplitude  $M_1$  ( $M_3/M_1$ ) in solid and  
16 liquid states for (a) samples (sam.) III and IV, (b) simulations (sim.) A, B, and C, and (c) distributions  
17 (dis.) A, B, and C. The flux density and frequency of the AC field are 10 mT and 10 kHz, respectively,  
18 in all cases.

	Sam. III	Sam. IV	Sim. A	Sim. B	Sim. C	Dis. A	Dis. B	Dis. C
$M_3$ (Solid)	0.0229	0.0334	0.0178	0.0447	0.0471	0.00103	0.128	0.00925
$M_3$ (Liquid)	0.0330	0.0589	0.0286	0.0729	0.0807	0.000541	0.209	0.0268
$M_3$ (Liquid/Solid)	1.44	1.76	1.61	1.63	1.71	0.523	1.64	2.90
$M_3/M_1$ (Solid)	0.0890	0.0838	0.0874	0.122	0.108	0.0104	0.148	0.0270
$M_3/M_1$ (Liquid)	0.115	0.123	0.123	0.173	0.149	0.00491	0.208	0.0531

19  
20 **4. Conclusions**

21 We evaluated the dependences of the effective size and the effective anisotropy, influenced by the  
22 particle structures, on the magnetization harmonic. The measurements of the MPI signal indicated that  
23  $M_3$  and  $M_3/M_1$  were applicable as the evaluation indexes of the harmonic amplitude and FWHM,  
24 respectively. A large core diameter induced large  $M_3$  and  $M_3/M_1$ , and large anisotropy increased the

1 ratio of  $M_3$  in the liquid state to that in the solid state. In contrast, when the anisotropy was small with  
2 respect to the MNPs with a large core diameter,  $M_3$  and  $M_3/M_1$  were large in the solid and liquid states.  
3 Consequently, it was revealed that the multicore structure induced the nonlinear response of the  
4 magnetization as the steep magnetization curve because of the large effective core diameter and small  
5 effective anisotropy. The anisotropy of the chainlike structure was large owing to unidirectional dipole  
6 interaction. Thus, the structure with a large core diameter and small anisotropy, such as the multicore  
7 structure, played a key role in the large amplitude of the MPI signal and the high resolution, which is  
8 also satisfied by the single-core structure with large core diameter, isotropic shape, and small  
9 magnetocrystalline anisotropy. On the contrary, the difference of the MPI signal between the states of  
10 MNPs, for instance, in tumors, organs, and blood, whose viscosity is changes with human health, was  
11 enhanced by the chainlike structure due to the large anisotropy. However, because the harmonic  
12 amplitude in the chainlike structure is lower than that of the multicore structure, it is necessary that the  
13 ratio between the MNPs of the chainlike and other structures was adjusted to keep the resolution high  
14 enough for detecting the MPI signal.

15

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19

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