

FLOWS AND FUNCTION ALGEBRAS OF GENERALIZED ANALYTIC FUNCTIONS

By

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Let X be a compact Hausdorff space and let (R, X) be a flow. This means that we are given a group homomorphism $t \rightarrow T_t$ from the real line R into the group of homeomorphisms of X with the property that the function $(t, p) \rightarrow T_t p$ from $R \times X$ to X is continuous. We denote by $C(X)$ the set of all continuous complex-valued functions on X , and by $H^\infty(R)$ the set of all continuous functions on R which admit bounded analytic extensions into the upper half-plane. We put $\mathfrak{A}_X = \{f \in C(X); f \circ T(t, x) \in H^\infty(R) \text{ for every } x \in X\}$, then \mathfrak{A}_X is a uniformly closed subalgebra of $C(X)$. But \mathfrak{A}_X need not be a function algebra.

In [2], Forelli showed that:

1) If the flow (R, X) is minimal, then \mathfrak{A}_X is a maximal pervasive subalgebra of $C(X)$.

In [5] and [6], Muhly showed that:

2) If the flow (R, X) is strictly ergodic, then \mathfrak{A}_X is a Dirichlet algebra and its maximal ideal space is completely determined.

In this paper, we defined the normalized flow (R, \tilde{X}) of the flow (R, X) so that $\mathfrak{A}_{\tilde{X}}$ is a function algebra and \mathfrak{A}_X is isometric-isomorphic to $\mathfrak{A}_{\tilde{X}}$. In Sections 1 and 2, we study some properties of \mathfrak{A}_X . In Section 3, we give necessary and sufficient conditions of normalized flows (R, X) for which \mathfrak{A}_X is essential, antisymmetric, analytic, pervasive and maximal, respectively.

§1. A normalized flow (R, X) and a maximal ideal space of \mathfrak{A}_X .

Recall that if A is a function algebra on a compact Hausdorff space Y , then a probability measure m on Y is called a representing measure for A if $\int_Y f g dm = \int_Y f dm \int_Y g dm$ for every $f, g \in A$. Let X be a compact Hausdorff space and let (R, X) be a flow. We write $M(X)$ the set of all bounded Baire measures on X . For $\mu \in M(X)$ and $t \in R$, we put $T_t \mu(E) = \mu(T_{-t} E)$ for every Baire set E of X . A measure $\mu \in M(X)$ is called quasi-invariant if $T_t \mu$ is absolutely continuous with respect to μ for each $t \in R$, and $\mu \in M(X)$ is called T_t -invariant if $T_t \mu(E) = \mu(E)$

for every $t \in R$ and for every Baire set E of X . For $\varphi \in C(X)$ and $f \in L^1(R)$, we put $T_t\varphi(x) = \varphi(T_{-t}x)$ for $x \in X$ and $t \in R$, and $\varphi * f = \int_{-\infty}^{\infty} (T_t\varphi)f(t)dt$. Then we have $\varphi * f \in C(X)$. For $\mu \in M(X)$ and $f \in L^1(R)$, $\mu * f$ is defined to be the measure such that $\int \varphi d\mu * f = \int \varphi * \tilde{f} d\mu$ for all $\varphi \in C(X)$, where \tilde{f} is the function whose value at $t \in R$ is $f(-t)$. For $\mu \in M(X)$ and $\varphi \in C(X)$, we put $J(\varphi) = \{f \in L^1(R); \varphi * f = 0\}$ and $J(\mu) = \{f \in L^1(R); \mu * f = 0\}$. Then $J(\varphi)$ and $J(\mu)$ are closed ideals of $L^1(R)$. We denote by $sp(\varphi)$ ($sp(\mu)$) the intersection of the zero sets of the Fourier transforms of the functions in $J(\varphi)$ ($J(\mu)$).

Lemma 1. ([5], p. 114) *Let (R, X) be a flow, then $\mathfrak{A}_X = \{\varphi \in C(X); sp(\varphi) \subset [0, \infty)\}$.*

Lemma 2. ([5], p. 116) *If μ is a representing measure for \mathfrak{A}_X which is not a point measure, then μ is quasi-invariant.*

Lemma 3. ([8], p. 57) *If a real measure $\mu \in M(X)$ satisfies $\int f d\mu = 0$ for every $f \in \mathfrak{A}_X$ ($\mu \perp \mathfrak{A}_X$), then μ is T_t -invariant.*

We put $P = \{x \in X; T_t x = x \text{ for every } t \in R\}$, then P is a compact subset of X . At first, we note that \mathfrak{A}_X need not separate the points of X . And by Lemma 3, we have that if $f(x) = f(y)$ for every $f \in \mathfrak{A}_X$ then $x, y \in P$.

For a given flow (R, X) , we will construct a new flow (R, \tilde{X}) as follows. For $x, y \in X$, we put $x \sim y$ iff $f(x) = f(y)$ for every $f \in \mathfrak{A}_X$. Then \sim is an equivalence relation on X . For $x \in X$, we denote by \tilde{x} the equivalence class of x . With the quotient topology, $\tilde{X} = X/\sim$ is a compact Hausdorff space and let $\phi: X \rightarrow \tilde{X}$ be the natural map. For $t \in R$ and $\tilde{x} \in \tilde{X}$, we put $T_t \tilde{x} = \tilde{T}_t x$, then T_t is a homeomorphism of \tilde{X} to \tilde{X} .

Proposition 1. $\{T_t\}_{t \in R}$ induces a flow on \tilde{X} .

Proof. It is sufficient to show that $R \times \tilde{X} \ni (t, \tilde{x}) \rightarrow T_t \tilde{x} \in \tilde{X}$ is continuous. Let $U(T_t \tilde{x})$ be an open neighborhood of $T_t \tilde{x}$ in \tilde{X} . We note that $\phi^{-1}(\tilde{x}) = \{x\}$, then $\phi^{-1}(\tilde{x}) \subset P$. For each $y \in \phi^{-1}(\tilde{x})$, there are a neighborhood $V_y(t)$ of t in R and a neighborhood $V(y)$ of y in X such that $T_u z \in \phi^{-1}(U(T_t \tilde{x}))$ for every $u \in V_y(t)$ and $z \in V(y)$. Since $\phi^{-1}(\tilde{x})$ is compact, there are $y_1, \dots, y_n \in \phi^{-1}(\tilde{x})$ such that $\bigcup_{i=1}^n V(y_i) \supset \phi^{-1}(\tilde{x})$. We put $V(t) = \bigcap_{i=1}^n V_{y_i}(t)$, then $T_u z \in \phi^{-1}(U(T_t \tilde{x}))$ for every $u \in V(t)$ and $z \in \bigcup_{i=1}^n V(y_i)$. Since $\bigcup_{i=1}^n V(y_i)$ is open and $\bigcup_{i=1}^n V(y_i) \supset \phi^{-1}(\tilde{x})$, we have that $(\bigcup_{i=1}^n V(y_i))^\circ$ is compact, $\phi((\bigcup_{i=1}^n V(y_i))^\circ)$ is compact in \tilde{X} and $\tilde{x} \in (\phi((\bigcup_{i=1}^n V(y_i))^\circ))^\circ$. We put $V_1 = (\phi((\bigcup_{i=1}^n V(y_i))^\circ))^\circ$, then V_1 is an open neighborhood of \tilde{x} . Since $T_u z \in \phi^{-1}(U(T_t \tilde{x}))$ for every $u \in V(t)$ and $z \in \bigcup_{i=1}^n V(y_i)$, we have $T_u \tilde{z} \in U(T_t \tilde{x})$ for $u \in V(t)$ and $\tilde{z} \in V_1$. This

implies that $R \times \tilde{X} \ni (t, \tilde{x}) \rightarrow T_t \tilde{x} \in \tilde{X}$ is continuous.

By Proposition 1, \mathfrak{A}_X is isometric-isomorphic to $\mathfrak{A}_{\tilde{X}}$, and $\mathfrak{A}_{\tilde{X}}$ separates the points of \tilde{X} . So that $\mathfrak{A}_{\tilde{X}}$ is a function algebra on \tilde{X} . The flow (R, \tilde{X}) is called the normalization of the flow (R, X) . In the rest of this paper, we assume that a flow (R, X) is normalized, that is, \mathfrak{A}_X is a function algebra on X .

Next, for a normalized flow (R, X) , we study the maximal ideal space of \mathfrak{A}_X . Let X_1 be the maximal ideal space of \mathfrak{A}_X . For $p \in X_1$, let m_p be one of the representing measures on X of p . For $t \in R$, we have $T_t f \in \mathfrak{A}_X$ for every $f \in \mathfrak{A}_X$. And we have that for $f, g \in \mathfrak{A}_X$,

$$\begin{aligned} \int fgdT_{t,m_p} &= \int T_{-t}fT_{-t}gdm_p = \int T_{-t}fdm_p \int T_{-t}gdm_p \\ &= \int fdT_{t,m_p} \int gdT_{t,m_p}. \end{aligned}$$

This implies that $T_t m_p$ is a representing measure for \mathfrak{A}_X . If μ_1 and μ_2 are representing measures for \mathfrak{A}_X of the same point $p \in X_1$, then $T_t \mu_1$ and $T_t \mu_2$ are representing measures for \mathfrak{A}_X of the same point of X_1 . Because,

$$\begin{aligned} \left\{ f \in \mathfrak{A}_X; \int fdT_{t,\mu_1} = 0 \right\} &= \left\{ f \in \mathfrak{A}_X; \int T_{-t}fd\mu_1 = 0 \right\} = \left\{ f \in \mathfrak{A}_X; \int T_{-t}fd\mu_2 = 0 \right\} \\ &= \left\{ f \in \mathfrak{A}_X; \int fdT_{t,\mu_2} = 0 \right\}. \end{aligned}$$

For $t \in R$ and $p \in X_1$, we denote by $T_t p$ the point of X_1 which is represented by $T_t m_p$. Then $T_t: X_1 \rightarrow X_1$ is a one-to-one onto map. Moreover, we have

Proposition 2. $\{T_t\}_{t \in R}$ induces the flow on X_1 .

Proof. (a) $T_t: X_1 \rightarrow X_1$ is a homeomorphism. It is sufficient to show that $T_t: X_1 \rightarrow X_1$ is continuous. Let $p_\alpha \rightarrow p$ in X_1 and $f \in \mathfrak{A}_X$. Then $\hat{f}(T_t p_\alpha) = \int fdT_{t,m_{p_\alpha}} = \int T_{-t}fdm_{p_\alpha} \rightarrow \int T_{-t}fdm_p = \hat{f}(T_t p)$. This implies that $T_t: X_1 \rightarrow X_1$ is continuous.

(b) For $f \in \mathfrak{A}_X$ and $\epsilon > 0$, there exists $\delta > 0$ such that $\|T_t f - f\|_\infty < \epsilon$ for every real number $|t| < \delta$. Because, suppose that there are $x_n \in X$ and $t_n \in R$ ($n=1, 2, \dots$) such that $|f(T_{t_n} x_n) - f(x_n)| > \epsilon$ for every positive integer n and $t_n \rightarrow 0$ ($n \rightarrow \infty$). We may assume that $x_i \neq x_j$ if $i \neq j$. Then there is $x_0 \in X$ which is contained in the cluster points of $\{x_i\}_{i=1}^\infty$ in X . Let U be a neighborhood of x_0 in X such that $|f(y) - f(x_0)| < \epsilon/2$ for every $y \in U$. Since $R \times X \rightarrow X$ is continuous, there exist a neighborhood V_1 of x_0 in X and an interval $I = [-\eta, \eta]$ ($\eta > 0$) such that $T_t y \in U$ for every $t \in I$ and $y \in V_1$. Since x_0 is a cluster point of $\{x_i\}_{i=1}^\infty$, there is a sufficient large integer n_0 such that $x_{n_0} \in V_1$ and $t_{n_0} \in I$. Since $T_{t_{n_0}} x_{n_0} \in U$ and $x_{n_0} \in U$,

we have

$$|f(T_{t_{n_0}}x_{n_0})-f(x_0)| < \frac{\varepsilon}{2} \quad \text{and} \quad |f(x_{n_0})-f(x_0)| < \frac{\varepsilon}{2}.$$

These imply that $|f(T_{t_{n_0}}x_{n_0})-f(x_{n_0})| < \varepsilon$. This is a contradiction and this completes the proof.

(c) $R \times X_1 \ni (t, p) \rightarrow T_t p \in X_1$ is continuous. Let $t_n \rightarrow t$ in R and $p_\beta \rightarrow p$ in X_1 . We show that $T_{t_n} p_\beta \rightarrow T_t p$. For $f \in \mathfrak{A}_X$, we have

$$\begin{aligned} \left| \int f dT_{t_n} m_{p_\beta} - \int f dT_t m_p \right| &\leq \left| \int f dT_{t_n} m_{p_\beta} - \int f dT_t m_{p_\beta} \right| + |\widehat{T_{-t} f}(p_\beta) - \widehat{T_{-t} f}(p)| \\ &\leq \|T_{-t_n} f - T_{-t} f\|_\infty + |\widehat{T_{-t} f}(p_\beta) - \widehat{T_{-t} f}(p)| \\ &\rightarrow 0 \quad (n \rightarrow \infty, \beta \rightarrow \infty) \quad \text{by (b)}. \end{aligned}$$

These imply that $R \times X_1 \ni (t, p) \rightarrow T_t p \in X_1$ is continuous. This completes the proof.

Let $\hat{\mathfrak{A}}_X$ be the set of all Gelfand transforms of $f \in \mathfrak{A}_X$, then $\hat{\mathfrak{A}}_X \subset C(X_1)$. We have the following.

Proposition 3. $\hat{\mathfrak{A}}_X \subset \mathfrak{A}_{X_1}$.

Proof. For $p \in X_1$ and $f \in \mathfrak{A}_X$, we show that $\hat{f}(T_t p) \in H^\infty(R)$. We put $F(t) = \int f dT_t m_p = \hat{f}(T_t p)$ and $G(t) = F(-t)$. By Proposition 2 of [1], we have $sp(G) \subset -sp(f) \cap sp(m_p) \subset (-\infty, 0]$. Since $sp(G) = -sp(F)$, we have $sp(F) \subset [0, \infty)$. Then $F \in H^\infty(R)$. This shows $\hat{\mathfrak{A}}_X \subset \mathfrak{A}_{X_1}$.

Remark 1. This fact implies that the flow (R, X_1) is normalized and $\mathfrak{A}_{X_1}|_X = \mathfrak{A}_X$, where $\mathfrak{A}_{X_1}|_X$ is the set of all functions of \mathfrak{A}_{X_1} restricted to X .

Remark 2. If $\mathfrak{A}_{X_1} \supsetneq \hat{\mathfrak{A}}_X$, then there is $f \in \mathfrak{A}_{X_1} \setminus \hat{\mathfrak{A}}_X$ such that $f \neq 0$ and $f=0$ on X . For, let $g \in \mathfrak{A}_{X_1} \setminus \hat{\mathfrak{A}}_X$, then there is $h \in \mathfrak{A}_X$ such that $g|_X = h$. We put $f = g - \hat{h}$ then f satisfies the above conditions.

§ 2. Some properties of \mathfrak{A}_X .

In this section, we show some basic facts about the function algebra \mathfrak{A}_X on the normalized flow (R, X) . For $x \in X$, we put δ_x the unit point mass at x . We denote by P_z the Poisson kernel for evaluation at z in the upper half plane, that is, $P_z(t) = y/\pi(y^2 + (x-t)^2)$, where $z = x + iy$, $y > 0$.

Lemma 4. ([6], Proposition 3.2) If m is a representing measure for \mathfrak{A}_X and if z is a point in the upper half plane, then $m * P_z$ is a representation measure for \mathfrak{A}_X .

Theorem 1. For a given normalized flow (R, X) , the following facts are equivalent.

- 1) $\mathfrak{A}_X = C(X)$.
- 2) $X = P$, where $P = \{x \in X; T_t x = x \text{ for every } t \in R\}$.
- 3) $X_1 = X$, where (R, X_1) is the normalized flow obtained in Proposition 2.
- 4) $\hat{\mathfrak{A}}_X = \mathfrak{A}_{X_1}$.

Proof. 2) \Rightarrow 1) \Rightarrow 3) are trivial.

3) \Rightarrow 2). Suppose that $X \not\equiv P$, then there exists $x \in X \setminus P$. Then $\delta_x * P_{iy}$ ($y > 0$) is a representing measure for \mathfrak{A}_X by Lemma 4. Since $x \notin P$, $\delta_x * P_{iy}$ is quasi-invariant and not invariant by Lemma 2. Suppose that $\delta_x * P_{iy}$ represents the point $z \in X$. Then $\delta_z - \delta_x * P_{iy}$ is invariant by Lemma 3. If $z \in P$, then $\delta_x * P_{iy}$ is invariant, and this is a contradiction. If $z \notin P$, then $\delta_z - \delta_x * P_{iy}$ is not invariant, and this is a contradiction. Then $\delta_x * P_{iy}$ does not represent the point of X . This shows $X_1 \not\equiv X$.

3) \Rightarrow 4) is trivial. 4) \Rightarrow 3). By the condition 4), the maximal ideal space of \mathfrak{A}_{X_1} is X_1 . So that we have $\mathfrak{A}_{X_1} = C(X_1)$ by the above argument. Then $\mathfrak{A}_{X_1}|_X = \mathfrak{A}_X = C(X)$, we have $X_1 = X$.

Remark 3. By the proof of Theorem 1, if μ is a representing measure for \mathfrak{A}_X which represents a point x of $X \setminus P$, then we have $\mu = \delta_x$. And this implies that every point $x \in X \setminus P$ is a Choquet boundary point of X .

Proposition 4. Let (R, X) be a normalized flow. Then the Shilov boundary of \mathfrak{A}_X is X .

Proof. Let ∂X be the Shilov boundary of \mathfrak{A}_X , then by Remark 3 we have $X \setminus \partial X \subset P$. Let $x_0 \in \text{Int } P$, the interior of P in X , and $U(x_0)$ be an open neighborhood of x_0 such that $U(x_0) \subset \text{Int } P$. For $f \in \mathfrak{A}_X$, there is a continuous function g on $U(x_0)$ such that $\tilde{f}(x) \in \mathfrak{A}_X$ and $|\tilde{f}(x_0)| > \sup_{x \in U(x_0)} |\tilde{f}(x)|$, where

$$\tilde{f}(x) = \begin{cases} f(x) & \text{if } x \notin U(x_0) \\ g(x) & \text{if } x \in U(x_0) \end{cases}$$

This shows that $X = \partial X$.

Proposition 5. Let (R, X) be a normalized flow and $x \in X$. If there is a neighborhood $U(x)$ of x in X_1 such that $U(x) \subset X$, then $x \in \text{Int } P$.

Proof. Let $x \notin \text{Int } P$ and $U(x)$ an open neighborhood of x in X_1 . Then there is $y \in U(x) \cap X$ such that $y \notin P$. For $z > 0$, $\delta_y * P_{iz}$ is a representing measure for \mathfrak{A}_X which represents a point in $X_1 \setminus X$. We note that $\{P_{it}\}_{t>0}$ is an approximate identity

for $L^1(R)$. Then we have $\lim_{t \rightarrow 0} \|f * \tilde{P}_{it} - f\|_\infty = 0$ for $f \in \mathfrak{A}_X$ by Lemma 1 of [1]. For $f \in \mathfrak{A}_X$, we have $\left| \int f d\delta_y * P_{it} - \int f d\delta_y \right| = \left| \int (f * \tilde{P}_{it} - f) d\delta_y \right| \rightarrow 0$ ($t \rightarrow 0$). This is a contradiction.

§ 3. Function algebra \mathfrak{A}_X .

In this section, we give necessary and sufficient conditions of normalized flows (R, X) for which \mathfrak{A}_X is essential, antisymmetric, analytic, pervasive and maximal, respectively. Let $P = \{x \in X; T_t x = x \text{ for every } t \in R\}$, then P is a compact subset of X . We put $H = \overline{X \setminus P}$. For a function algebra A on Y , there exists a unique minimal closed subset $E \subset Y$, called the essential set for A , such that if $f \in C(Y)$ and f vanishes on E then $f \in A$. We say that the function algebra A on Y is essential if the essential set for A coincides with Y .

Proposition 6. *For a normalized flow (R, X) , H is the essential set for \mathfrak{A}_X .*

Proof. If $f \in C(X)$ and $f = 0$ on H , then easily we have $f \in \mathfrak{A}_X$. Let E be a closed set with $E \subsetneq H$. There exists $x \in H \setminus E$ such that $x \notin P$. Then there is an interval $I = [-\varepsilon, \varepsilon]$ such that $\{T_t x; t \in I\} \cap E = \emptyset$. Then there exists $g \in C(X)$ such that $g = 0$ on E and $g|_{\{T_t x; t \in I\}} \neq h|_{\{T_t x; t \in I\}}$ for every $h \in \mathfrak{A}_X$. Because $\{T_t x; t \in I\}$ is not an interpolation set for \mathfrak{A}_X . This implies that E is not an essential set for \mathfrak{A}_X , so that H is an essential set for \mathfrak{A}_X .

By Proposition 6, we have

Theorem 2. *Let (R, X) be a normalized flow. Then \mathfrak{A}_X is an essential algebra iff $\text{Int } P = \emptyset$.*

For a function algebra A on Y , a closed subset E of Y is called a set of antisymmetric for A if $f \in A$ and $f|_E$ real implies $f|_E$ is constant. If Y is a set of antisymmetric for A , A is called antisymmetric. For $x \in X$, we put $O(x) = \{T_t x; t \in R\}$.

Lemma 5. *Let $\varphi \in C(X)$, then $sp(\varphi) = \{0\}$ iff $\varphi|_{O(x)}$ is constant for each $x \in X$.*

Proof. (\Leftarrow) Let $\varphi \in C(X)$ and $\varphi|_{O(x)}$ is constant for each $x \in X$. Then we have $J(\varphi) = \{f \in L^1(R); \hat{f}(0) = 0\}$, where \hat{f} is the Fourier transform of f . Then $sp(\varphi) = \{0\}$.

(\Rightarrow) Suppose that $\varphi|_{O(x)}$ is not constant for some $x \in X$. Then there is $g \in L^1(R)$ such that $\hat{g}(0) = 0$ and $\varphi * g(x) \neq 0$. So that we have $J(\varphi) \neq \{f \in L^1(R); \hat{f}(0) = 0\}$. Since $\{0\} \subset R$ is the set of spectral synthesis, we have $sp(\varphi) \neq \{0\}$.

Lemma 6. *If $\varphi \in C(X)$ and $\varphi|_{O(x)}$ is constant for each $x \in X$, then $\varphi \in \mathfrak{A}_X$.*

Proof. This is a trivial fact.

Theorem 3. *Let (R, X) be a normalized flow. Then \mathfrak{A}_X is antisymmetric iff $\varphi \in C(X)$ and $sp(\varphi) = \{0\}$ imply φ is constant.*

Proof. (\Leftarrow) Let $f \in \mathfrak{A}_X$ be a real function, then $f|_{O(x)}$ is constant for every $x \in X$. By Lemma 6, we have $sp(\varphi) = \{0\}$. By the condition, φ is constant.

(\Rightarrow) Suppose that there exists $\varphi \in C(X)$ such that φ is not constant and $sp(\varphi) = \{0\}$. By Lemma 6, $\varphi|_{O(x)}$ is constant for each $x \in X$. If $|\varphi|$ is not constant, then $|\varphi| \in \mathfrak{A}_X$ by Lemma 6 and \mathfrak{A}_X is not antisymmetric. If $|\varphi|$ is constant, there is a continuous function h on the complex plane such that $|h \circ \varphi|$ is not constant. Since $|h \circ \varphi| \in \mathfrak{A}_X$, \mathfrak{A}_X is not antisymmetric. This completes the proof.

A function algebra A on Y is called analytic if $f \in A$ vanishes on an open set of Y then $f=0$.

Theorem 4. *Let (R, X) be a normalized flow, then the following assertions are equivalent.*

- 1) \mathfrak{A}_X is analytic.
- 2) \mathfrak{A}_X is an integral domain.
- 3) Each T_t -invariant open set of X is dense in X .

Proof. 1) \Rightarrow 2) is a trivial fact.

2) \Rightarrow 3). Suppose that Q is a T_t -invariant open subset of X such that Q is not dense in X . We put $Q_1 = X \setminus \bar{Q}$, then Q_1 is a non-void T_t -invariant open subset of X . Here we can consider that (R, Q) and (R, Q_1) are flows on locally compact spaces Q and Q_1 , respectively. By Lemma 2 of [1], there are non-zero $f \in C_0(Q)$ and $g \in C_0(Q_1)$ such that $sp(f) \subset [0, \infty)$ and $sp(g) \subset [0, \infty)$, where $C_0(\cdot)$ is the set of all continuous functions which vanish at infinity. We put

$$\begin{aligned} \varphi_1(x) &= \begin{cases} f(x) & \text{if } x \in Q \\ 0 & \text{if } x \in X \setminus Q, \end{cases} \quad \text{and} \\ \varphi_2(x) &= \begin{cases} g(x) & \text{if } x \in Q_1 \\ 0 & \text{if } x \in X \setminus Q_1, \end{cases} \end{aligned}$$

then $\varphi_1, \varphi_2 \in \mathfrak{A}_X$, $\varphi_1 \neq 0$, $\varphi_2 \neq 0$ and $\varphi_1 \varphi_2 = 0$. This is a contradiction.

3) \Rightarrow 1) Let $f \in \mathfrak{A}_X$ and $f=0$ on an open set Q of X . Then $f=0$ on $\{T_t q, t \in R\}$ for every $q \in Q$, and $f=0$ on $\bigcup_{t \in R} T_t Q$. Since $\bigcup_{t \in R} T_t Q$ is dense in X , we have $f=0$.

A function algebra A on Y is called pervasive if for every closed subset $E \subseteq X$, $\mathfrak{A}_X|_E$ is sup-norm dense in $C(E)$.

Theorem 5. *If (R, X) is a normalized flow, then \mathfrak{A}_X is pervasive iff $\mathfrak{A}_X|_P$ is dense in $C(P)$ and a proper T_t -invariant closed subset of X is contained in P .*

Proof. (\Rightarrow) Suppose that there is a closed T_t -invariant subset $F \subsetneq X$ such that $F \not\subset P$. We note that (R, F) is a flow. Since $\mathfrak{A}_X|_F \subset \mathfrak{A}_F$ and $F \not\subset P$, we have $\mathfrak{A}_F \subsetneq C(F)$ by Theorem 1. Then $\mathfrak{A}_X|_F$ is not dense in $C(F)$.

(\Leftarrow) Suppose that \mathfrak{A}_X is not pervasive. Then there is a closed subset $F \subsetneq X$ such that $\overline{\mathfrak{A}_X|_F} = C(F)$. Then there exists a non-zero $\mu \in M(F)$ such that $\mu \perp \mathfrak{A}_X$. Since μ is quasi-invariant by Forelli [1], $\bigcup_{t \in Q} T_t F^\circ$ is an open μ -measure zero set, where Q is the set of rational numbers. We put $G = \bigcup_{t \in Q} T_t F^\circ$. Then $G = \bigcup_{t \in R} T_t F^\circ$. Since $\mu \in M(G^\circ)$, G° is non-void, closed and T_t -invariant. By the condition, we have $G^\circ \subset P$. Since $\mathfrak{A}_X|_P$ is dense in $C(P)$, we have $\mu = 0$. This is a contradiction.

A function algebra A on Y is called maximal if B is a closed subalgebra of $C(Y)$ such that $A \subset B \subset C(Y)$ then $B = A$ or $B = C(Y)$. A flow (R, Y) is called minimal if $O(x)$ is dense in Y for every $x \in Y$. In [2], Forelli showed that if (R, X) is minimal then \mathfrak{A}_X is maximal. Here we give a necessary and sufficient condition for which \mathfrak{A}_X is maximal. The proof is a precise modification of the proof of Forelli [2].

Lemma 7. ([2], Lemma 2.2) *If $F \in L^\infty(R)$, then $F \in H^\infty(R)$ iff $\int F(t)G(t)dt = 0$ for every G in $H^1(R)$.*

Lemma 8. ([2], Lemma 2.4) *If $\varphi \in C(X)$ and $f \in H^1(R)$, then $\int f(T_t x)F(-t)dt$ belongs to \mathfrak{A}_X .*

We put $U(t, x) = (t, T_t x)$ for $(t, x) \in R \times X$, then U is a homeomorphism of $R \times X$.

Lemma 9. ([2], Lemma 2.6) *Let $\lambda \in M(R)$ and $\mu \in M(X)$. If μ is quasi-invariant, then there is a finite non-negative Baire measurable function φ on $R \times X$ such that $\int f d(\lambda \times \mu) = \int (f \circ U) \varphi d(\lambda \times \mu)$ for all $f \in L^1(\lambda \times \mu)$.*

Theorem 6. *Let (R, X) be a normalized flow. Then \mathfrak{A}_X is maximal iff $\mathfrak{A}_X|_P$ is dense in $C(P)$ and $O(x)$ is dense in $X \setminus P$ for each $x \in X \setminus P$.*

Proof. (\Leftarrow) Let B be any closed subalgebra of $C(X)$ that contains \mathfrak{A}_X . Suppose that $B \neq C(X)$. Then there is a non-zero measure $\beta \in M(X)$ such that $\beta \perp B$. By Forelli [1], β is quasi-invariant, so that $|\beta|$ is quasi-invariant. For $G \in H^1(R)$ with $G \neq 0$, we put $d\lambda = G(t)dt$, and $\mu = |\beta|$, and let φ be a finite non-negative Baire measurable function on $R \times X$ which satisfies Lemma 9. Furthermore let Y and χ be bounded complex measurable functions on R and X , such that $G = Y|G|$ and $\beta = \chi\mu$, respectively. We denote by Z_+ the class of all non-negative integers and Q_+ the class of all non-negative rational numbers. First we note that, since $\mathfrak{A}_X|_P$ is dense in $C(P)$, we have

$$(1) \quad \beta \notin M(P).$$

We will show that $B \subset \mathcal{A}_X$. Let $g \in B$. We put $F(t, x) = e^{irt} Y(t) \chi(x) g(x)^k f(T_{-t}x)$, where $r \in \mathbb{Q}_+$, $k \in \mathbb{Z}_+$ and $f \in C(X)$. Then we have

$$(2) \quad \begin{aligned} \int F d(\lambda \times \mu) &= \iint e^{irt} Y(t) \chi(x) g(x)^k f(T_{-t}x) d\lambda(t) d\mu(x) \\ &= \int \left(\int f(T_{-t}x) e^{irt} G(t) dt \right) g(x)^k d\beta \quad \text{and} \end{aligned}$$

$$(3) \quad \begin{aligned} \int (FU)\varphi d(\lambda \times \mu) &= \iint e^{irt} Y(t) \chi(T_t x) g(T_t x)^k f(x) \varphi(t, x) d\lambda(t) d\mu(x) \\ &= \int \left(\int e^{irt} G(t) \chi(T_t x) \varphi(t, x) g(T_t x)^k dt \right) f(x) d\mu(x). \end{aligned}$$

Since $e^{irt} G(t) \in H^1(\mathbb{R})$, we have $\int F d(\lambda \times \mu) = 0$ by Lemma 8. By Lemma 9, we have $\int (F \circ U)\varphi d(\lambda \times \mu) = 0$ for every $f \in C(X)$. Therefore

$$\int e^{irt} G(t) \chi(T_t x) \varphi(t, x) g(T_t x)^k dt = 0$$

for μ almost all x . Since \mathbb{Q}_+ and \mathbb{Z}_+ are countable sets, there is a Baire set $N \subset X$ of μ measure 0 such that if $x \in N^c$, then

$$(4) \quad \int e^{irt} G(t) \chi(T_t x) \varphi(t, x) g(T_t x)^k dt = 0$$

for all $r \in \mathbb{Q}_+$ and all $k \in \mathbb{Z}_+$. We remark that if $x \in N^c$, then

$$(5) \quad \int |G(t) \chi(T_t x)| \varphi(t, x) dt < \infty.$$

By Lemma 9 (with $f(t, x) = |\chi(x)|$), we have

$$\|\lambda\| \|\mu\| = \int |\chi(x)| d(\lambda \times \mu) = \int |\chi(T_t x)| \varphi(t, x) d(\lambda \times \mu).$$

We put $\mu = \mu_1 + \mu_2$, where $\mu_1 \in M(P)$ and $\mu_2 \perp M(P)$. Then we have

$$\begin{aligned} \int |\chi(T_t x)| \varphi(t, x) d(\lambda \times \mu) &= \iint |\chi(T_t x)| \varphi(t, x) d\lambda(t) d\mu_1(x) + \iint |\chi(T_t x)| \varphi(t, x) d\lambda(t) d\mu_2(x) \\ &= \iint \varphi(t, x) d\lambda(t) d\mu_1(x) + (\cdot) \\ &= \iint \chi' d\lambda(t) d\mu_1(x) + (\cdot) \\ &= \|\lambda\| \|\mu_1\| + \iint |\chi(T_t x)| \varphi(t, x) d\lambda(t) d\mu_2(x), \end{aligned}$$

where χ' is a Baire function such that $\mu_1 = \chi' \mu$.

By (1), we have $\iint |\chi(T_i x)| \varphi(t, x) d\lambda(t) d\mu_2(x) > 0$. This implies that there is $x \in N^c$ with $x \in X \setminus P$ such that

$$(6) \quad \int |G(t) \chi(T_i x)| \varphi(t, x) dt > 0.$$

Fix such an x and we put $H(t) = G(t) \chi(T_i x)$, then $H(t) \in L^1(R)$ with $H(t) \neq 0$ by (5) and (6). By (4), we have $H(t) g(T_i x)^k \in H^1(R)$ for every $k \in Z_+$. Then we have $g(T_i x) \in H^\infty(R)$ by Gamelin ([3], p. 177). Since $H^\infty(R)$ is a translation invariant space, we have $g(T_i y) \in H^\infty(R)$ for every $y \in O(x)$, for each $x \in X$. Let $G \in H^1(R)$. Then $\int g(T_i z) G(t) dt \in C(X)$. By Lemma 7, we have $\int g(T_i y) G(t) dt = 0$ for every $y \in O(x)$. Since $O(x)$ is dense in $X \setminus P$, we have $\int g(T_i z) G(t) dt = 0$ for every $z \in X \setminus P$ and every $G \in H^1(R)$. By Lemma 7, we have $g(T_i z) \in H^\infty(R)$ for every $z \in X \setminus P$. Therefore $g(T_i z) \in H^\infty(R)$ for every $z \in X$ and we have $g \in \mathfrak{A}_X$.

(\Rightarrow) *Case I.* Suppose that there is $x \in X \setminus P$ such that $\overline{O(x)} \cup P \subsetneq X$. Since $\overline{O(x)}$ is a T_i -invariant set, $(R, \overline{O(x)})$ is a normalized flow. We put $B = \{f \in C(X); f|_{\overline{O(x)}} \in \mathfrak{A}_{\overline{O(x)}}\}$, then B is a closed subalgebra of $C(X)$. Since $\mathfrak{A}_{\overline{O(x)}} = C(\overline{O(x)})$, we have $B \subsetneq C(X)$. Since there exists $y \in X \setminus \overline{O(x)}$ with $y \notin P$, we have $\mathfrak{A}_X \subsetneq B$.

Case II. Suppose that $\mathfrak{A}_X|_P$ is not dense in $C(P)$. We put $B' = \{f \in C(X); f|_P \in \overline{\mathfrak{A}_X|_P}\}$, then easily we have $\mathfrak{A}_X \subsetneq B' \subsetneq C(X)$.

Corollary 2. *Let (R, X) be a normalized flow. Suppose that \mathfrak{A}_X is essential, then we have that \mathfrak{A}_X is pervasive iff \mathfrak{A}_X is maximal.*

Proof. (\Rightarrow) Suppose that \mathfrak{A}_X is not maximal. By Theorem 6, there is a T_i -invariant closed subset $F \subsetneq X$ such that $F \not\subset P$. Then there is $x \in F \setminus P$, and $\overline{O(x)} \subset F$. If $O(x)$ is dense in $X \setminus P$, then $X \setminus P \subset F$ and this contradicts with $\text{Int } P = \emptyset$. Consequently, $O(x)$ is not dense in $X \setminus P$, and $\overline{O(x)} \supset X \setminus P$. By Theorem 5, \mathfrak{A}_X is not pervasive.

(\Leftarrow) For $x \in X \setminus P$, we have $\overline{O(x)} = X$. This implies that $O(x)$ is dense in X . By Theorem 5, this completes the proof.

Note added in proof. Professor Tomiyama points out that $\text{int } P$, the interior of P in X , is open in X_1 by his paper: Some remarks on antisymmetric decompositions of function algebras, Tôhoku Math. J., 16 (1964), 340-344. Because let Q be the collection of all antisymmetric sets of \mathfrak{A}_X in X which consist of a single point, and let Q^i be the essential set of \mathfrak{A}_X in X by Theorem 3 of Tomiyama's paper. By Proposition 6, we have $\overline{X \setminus P} = X \setminus Q^i$ so that $\text{int } P = Q^i$.

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